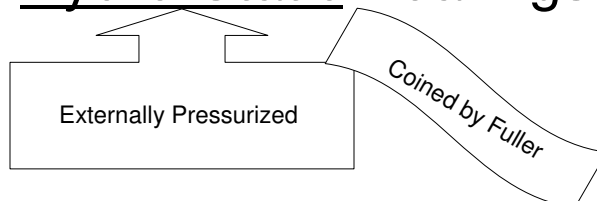


Hydrostatic Bearings: An Introduction

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Design Procedure for Hydro-Static Bearings (HSB)



- Invented by L. D. Girard (Frenchman).
- Completely removal of wear and reduction of coefficient of friction to 1/500.
- Machines using hydrostatic support show a better rotational accuracy within 2 micro-inch (0.051 micron) and RMS surface roughness down to 0.25 micro-inch (0.00635 micron)

Features of Hydrostatic support

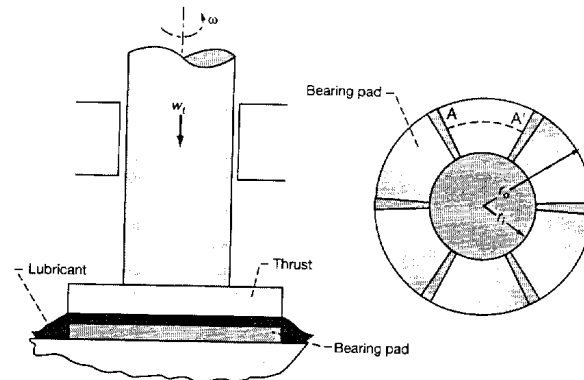
- Surfaces can be separated by full fluid film even at zero speed.
 - No problem with micro roughness and waviness.
- Zero friction at zero speed.
 - Useful feature for large size telescopes and radars.
- High stiffness
 - Oil film thickness varies as cube root of load. $h \propto W^{1/3}$
- Why not every bearing is based on Hydrostatic mechanism
 - High pressure supply... Reliability & life of high pressure oil lines are always in doubt.

HSB for Large Binocular Telescope

- Supports for Azimuth and Elevation axes.
 - Telescope makes a far away object look closer by collecting light from a distant object (objective lens or primary mirror) and brings that light (image) to a focus where a second device (eyepiece lens) magnifies the image and brings it to our eye.
 - A telescope's ability to collect light is directly related to the diameter of the lens or mirror -- the **aperture** -- that is used to gather light. Generally, the larger the aperture, the more light the telescope collects and brings to focus, and the brighter the final image.
 - Refractors have good resolution, high enough to see details. However, it is difficult to make large objective lenses (greater than 4 inches or 10 centimeters) for refractors. Because the aperture is limited, a refractor is less useful for observing faint, deep-sky objects, like galaxies and nebulae, than reflector types of telescopes.

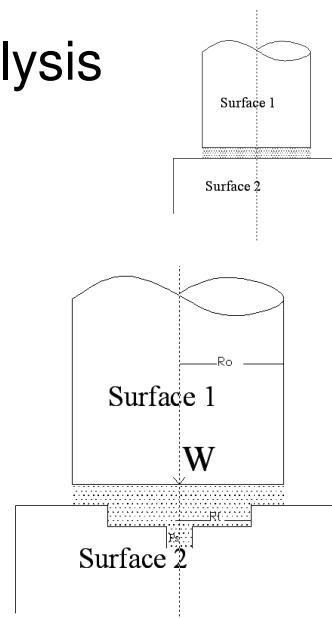
Thrust Bearings

- Many loads carried by rotating machinery have components that act in the direction of the shaft's axis of rotation. Bearings supporting such loads are known as thrust bearings.



Elementary 1-D Analysis

- Assume a shaft of radius R_o is located co-axially with a circular recess of radius R_i .
- Assume all the oil in recess is at the supply pressure P_s .



- Consider a small element of angular extent $d\theta$ at a radius r and radial width dr .

- Elemental flow rate: $\delta q = -\frac{h^3}{12\eta} \frac{dp}{dr} \cdot r d\theta$

- If flow is symmetrical to the origin, and radial flow rate is constant, then flow rate:

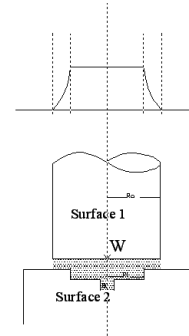
$$Q = -\frac{h^3}{12\eta} \frac{dp}{dr} \cdot r \cdot 2\pi$$

- If film thickness is constant, then on integration:

$$\frac{\pi h^3 p}{6\eta} = -Q (\log r + C_1)$$

- Using two boundary conditions to find unknown values of C_1 and Q

$$p = p_s \frac{\log \frac{R_0}{r}}{\log \frac{R_0}{R_i}} \quad \text{in the region } R_0 \geq r \geq R_i$$

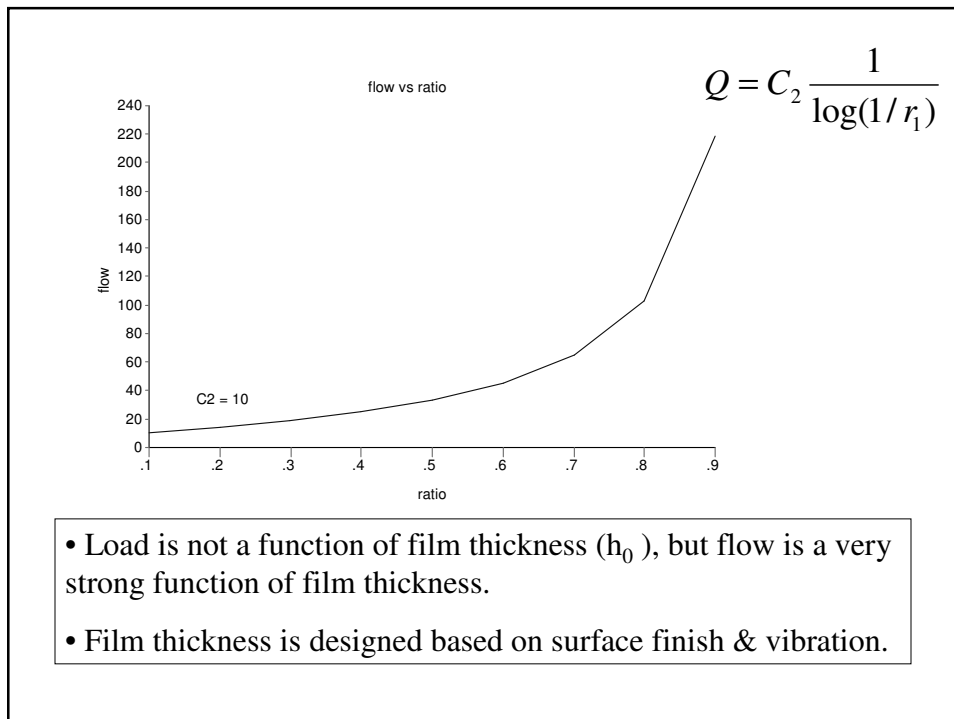
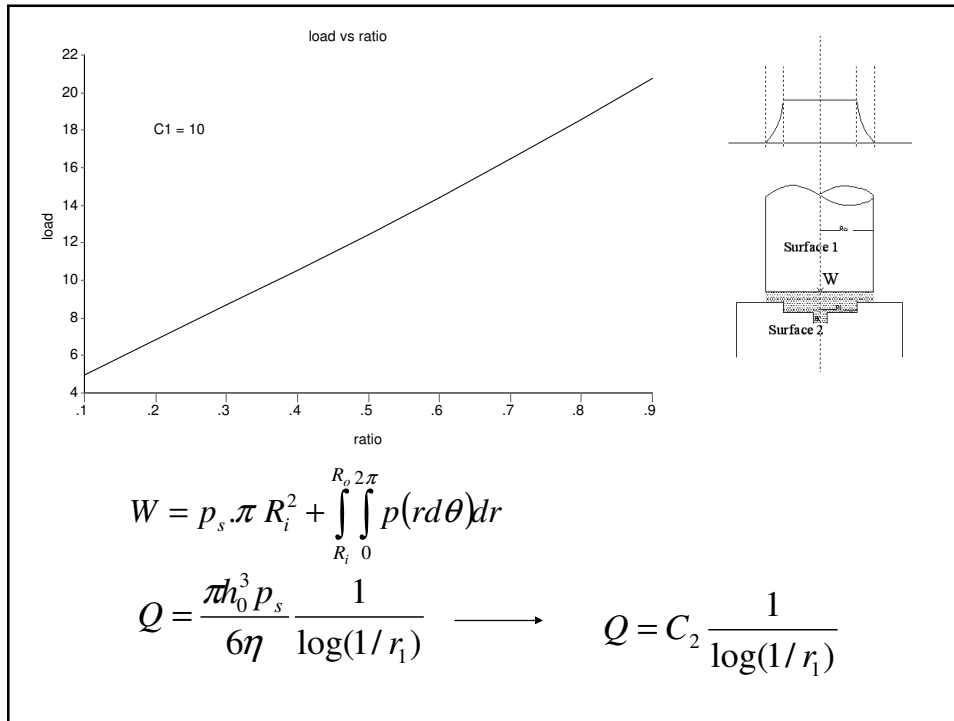


- Load carrying capacity:

$$W = p_s \cdot \pi R_i^2 + \int_{R_i}^{R_o} \int_0^{2\pi} p(r d\theta) dr$$

- Substituting expression of p and rearranging

$$W = p_s \cdot (\pi R_o^2) \left(\frac{1 - \frac{R_i^2}{R_o^2}}{2 \cdot \log \left(\frac{R_o}{R_i} \right)} \right) \longrightarrow W = C_1 \left(\frac{1 - r_1^2}{2 \cdot \log \left(\frac{1}{r_1} \right)} \right)$$



Power loss

- Power consumption in the hydrostatic bearing system consists of pumping power and friction losses.

$$P_t = P_h + P_f$$

$$P_h = Q \cdot P_s$$

$$P_f = \frac{\pi}{2} \eta \frac{R_0^4}{h_0} \left(1 - \left(\frac{R_i}{R_0} \right)^4 \right) \omega^2$$

$$F = \eta A \frac{U}{h_0}$$

$$F = \eta \frac{\omega r}{h_0} A(r)$$

$$P_f = F \omega r \Rightarrow P_f = \eta \frac{\omega^2}{h_0} \int_{R_i}^{R_0} 2\pi r^3 dr$$

Petroff equation

$$P_t = \frac{1}{\eta_1} \frac{1}{6\eta} \frac{\pi h_0^3}{\log(R_0 / R_i)} P_s^2 + \frac{1}{\eta_2} \frac{\pi}{2} \eta \frac{R_0^4}{h_0} \left(1 - \left(\frac{R_i}{R_0} \right)^4 \right) \omega^2$$

Example: $W = 1000 \text{ N}$, $\omega = 5000 \text{ rpm}$, $R_0 = 100 \text{ mm}$, $R_i = 50 \text{ mm}$, $\eta = 0.01 \text{ Pa}\cdot\text{s}$, $\eta_1 = 0.6$, $\eta_2 = 0.9$.
Optimize minimum film thickness for minimum power loss

$$P_t = \frac{1}{\eta_1} \frac{1}{6\eta} \frac{\pi h_0^3}{\log(R_0 / R_i)} P_s^2 + \frac{1}{\eta_2} \frac{\pi}{2} \eta \frac{R_0^4}{h_0} \left(1 - \left(\frac{R_i}{R_0} \right)^4 \right) \omega^2$$

$$W = p_s \cdot (\pi R_o^2) \left(\frac{1 - \frac{R_i^2}{R_o^2}}{2 \cdot \log\left(\frac{R_o}{R_i}\right)} \right)$$

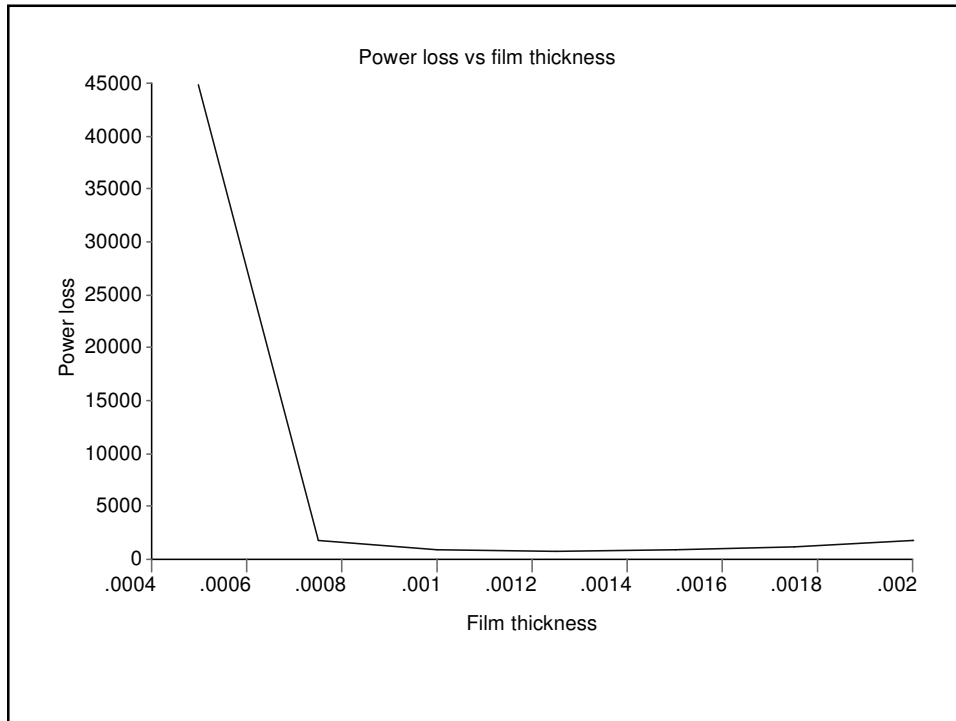
$$P_t = C_1 h_0^3 + C_2 / h_0$$

$$\omega = 2\pi \cdot 5000 / 60 \Rightarrow \omega = 523.6 \text{ rad/s}$$

$$P_s = \frac{1000}{\pi \cdot 0.1^2} \frac{2 \cdot \log(2)}{(1 - 0.5^2)} \Rightarrow P_s = 58,824 \text{ Pa}$$

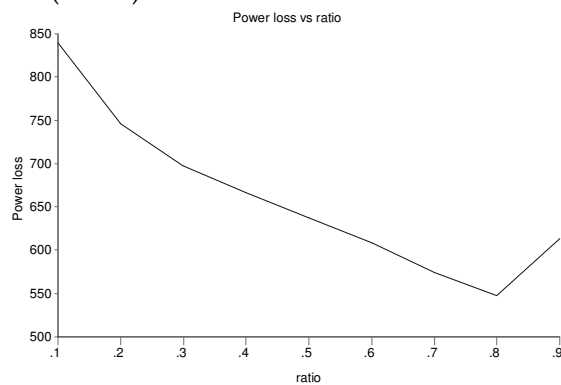
$$C_1 = 4.35 \cdot 10^{11} \text{ N}/(\text{s}\cdot\text{m}^2)$$

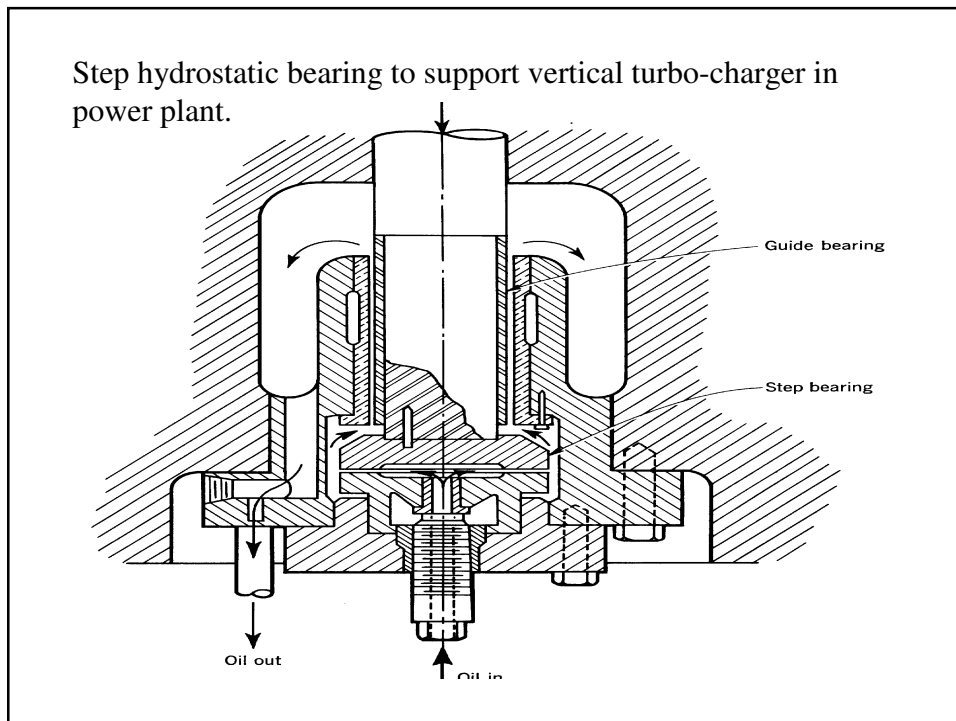
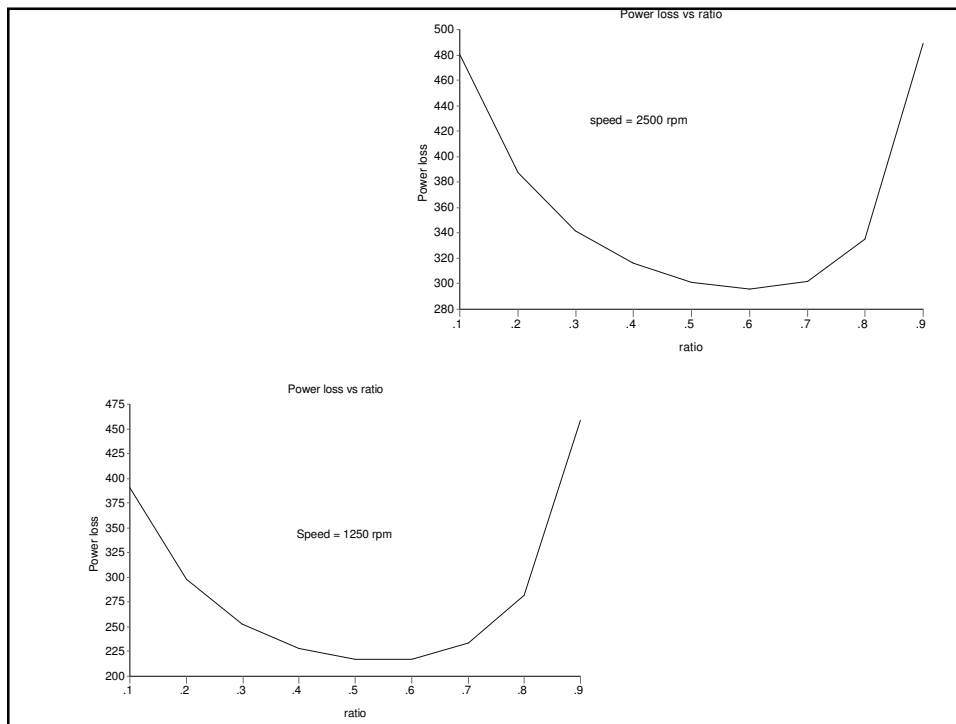
$$C_2 = 0.448 \text{ N}\cdot\text{m}^2 / \text{s}$$



Example: $W = 1000 \text{ N}$, $\omega = 5000 \text{ rpm}$, $R_0 = 100 \text{ mm}$,
 $\eta = 0.01 \text{ Pa.s}$, $\eta_1 = 0.6$, $\eta_2 = 0.9$, $h_0 = 1 \text{ mm}$. Optimize ratio
 (R_i/R_0) for minimum power loss

$$P_t = 353.5 \frac{\log(1/r)}{(1-r^2)^2} + 478.7 * (1-r^4)$$





Restrictor

- In earlier slides, it was assumed that recess pressure was equal to supply pressure.

$$W = p_s (\pi R_o^2) \left(\frac{1 - R_i^2 / R_o^2}{2 \cdot \log(R_o / R_i)} \right)$$

- This means change in load requires change in performance of pump.
- Pump performance can be regulated:
 - Manually
 - Automatically
- To automat the pump performance one needs sensor, amplifier, controller, etc.
- To reduce cost, often self regulating called restrictor is used.

Restrictor

- Constant flow restrictor $Q = \frac{\pi h_0^3 p_s}{6\eta} \frac{1}{\log(1/r_1)}$
 - If flow is constant, recess pressure and film thickness are related.
 - Increase in load, is balanced by increase in recess pressure and corresponding decrease in film thickness.
- Constant supply pressure restrictor
 - Recess pressure is kept lower than supply pressure
 - Drop in pressure, from supply pressure to recess pressure, depends is controlled by the fixed restrictor placed between supply manifold and the bearing.
 - Increase in load, reduces the flow by decreasing film thickness, recess pressure increases and equilibrium is restored.

Constant supply pressure restrictors

- Most commonly used restrictors are “capillary” and “orifice”.
 - Capillary is relatively long and narrow opposed to and orifice which is short in the direction of flow.
 - In a capillary, flow occurs due to shearing and is dependent on viscosity of fluid, whereas flow in orifice is due to inertia and depends on density.
 - Flow in capillary is directly proportional to pressure difference and that in an orifice is dependent on square root of pressure difference.
 - Although the pumping power losses are higher for these types of compensation devices, the initial cost is much less.

$$Q_c = \frac{\Delta P \pi R_c^4}{8 \eta l_c}$$

$$Q_o = \frac{\pi d_o^2}{4} C_D \sqrt{2 \Delta P / \rho}$$

A smaller flow produces a smaller pressure drop.

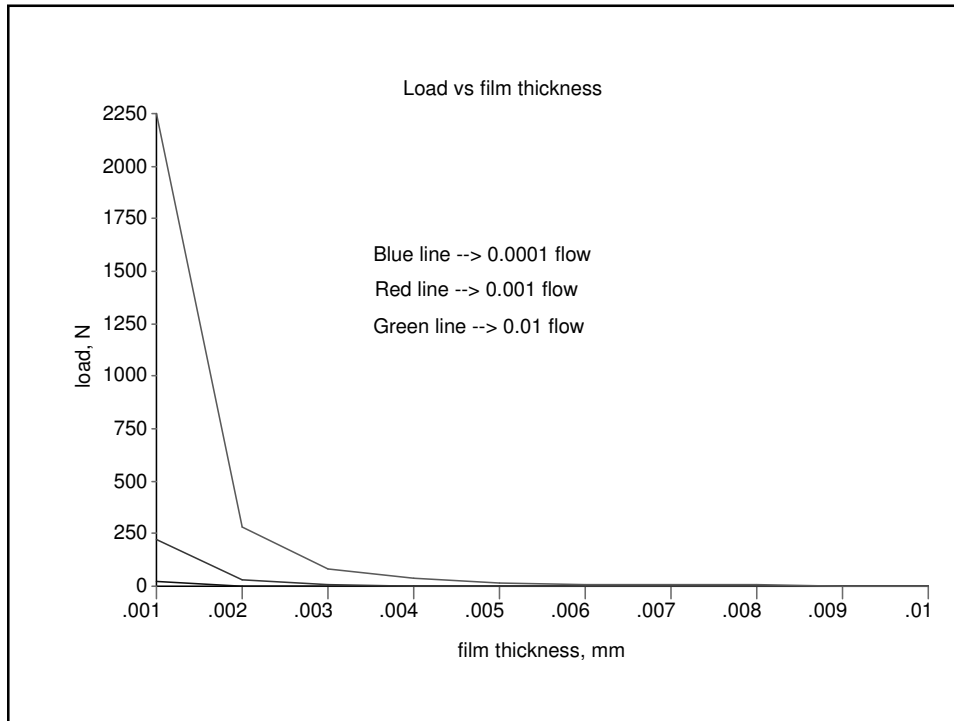
Hydrostatic Bearing Film Stiffness with Constant Feed Rate

$$Q = \frac{\pi h_0^3 P_s}{6 \eta \log(R_o / R_i)} \qquad W = p_s \cdot (\pi R_o^2) \left(\frac{1 - R_i^2 / R_o^2}{2 \cdot \log(R_o / R_i)} \right)$$

$$\Rightarrow W = 3 \eta \cdot R_o^2 \left(1 - \frac{R_i^2}{R_o^2} \right) \left(\frac{Q}{h_0^3} \right) \Rightarrow 3 * 0.01 * (0.1)^2 * (1 - 0.5^2) * \frac{Q}{h_0^3}$$

$$\text{Stiffness } K_1 = \frac{dW}{dh_0} = -\frac{3W}{h_0}$$

If W is doubled, and Q is kept constant, what will be relative change in film thickness?



Capillary Compensation

$$Q = \frac{\pi h_o^3 P_r}{6\eta \log(R_o/R_i)} \Rightarrow Q = B h_o^3 P_r \quad \text{--> } B = 174$$

$$Q_c = \frac{(P_s - P_r) \pi R_c^3}{8\eta l_c} \Rightarrow Q_c = k_c (P_s - P_r) \quad \text{--> assume } \eta = 0.01$$

$$r_c = 0.15 \text{ mm}, l_c = 50 r_c$$

$$Q = Q_c$$

$$\Rightarrow \frac{P_r}{P_s} = \frac{k_c}{B h_o^3 + k_c}$$

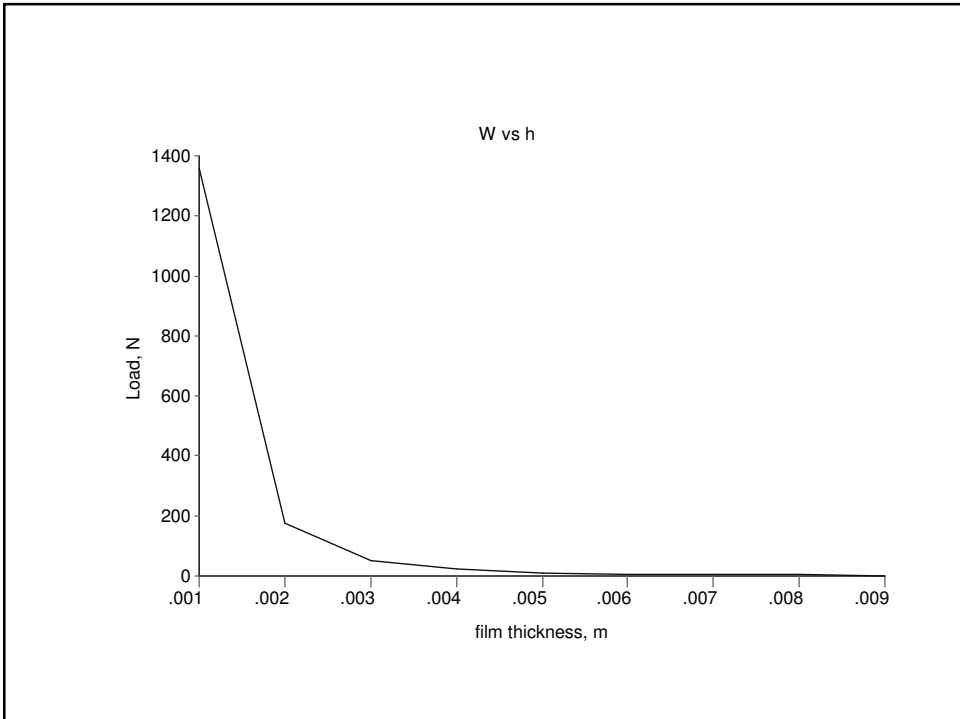
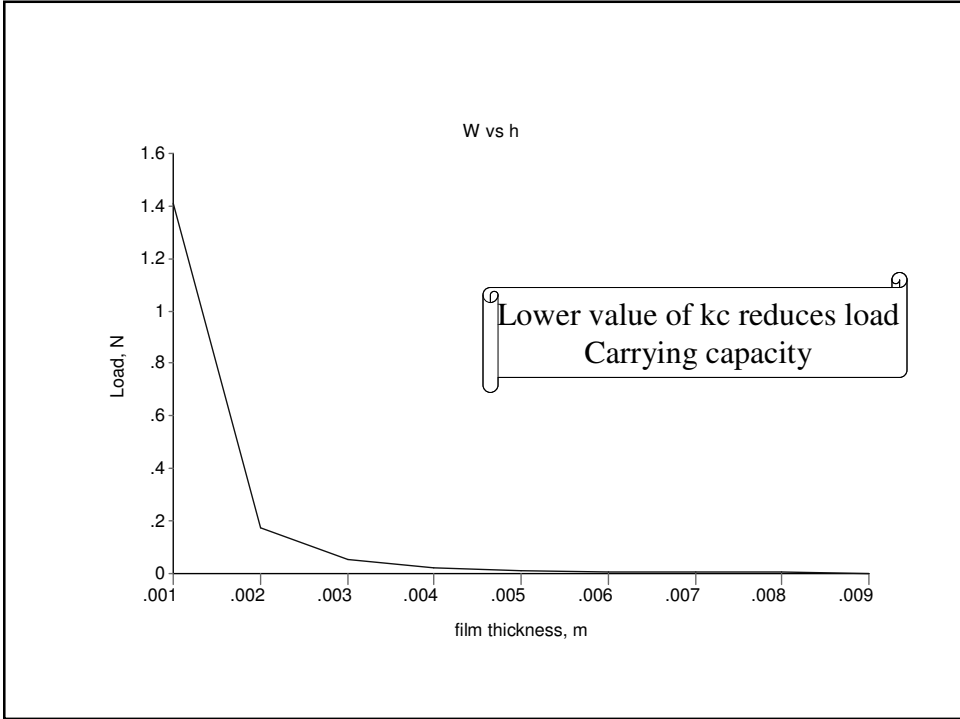
$$W = P_r (\pi R_o^2) \left(\frac{1 - R_i^2/R_o^2}{2 \log(R_o/R_i)} \right) \Rightarrow A_{eff} P_r$$

$$\Rightarrow W = A_{eff} P_s \frac{k_c}{B h_o^3 + k_c} \quad A_{eff} = 0.039$$

$$\frac{\partial W}{\partial h_o} = -A_{eff} P_s \frac{k_c}{B h_o^3 + k_c} \frac{3B h_o^2}{B h_o^3 + k_c}$$

$$\text{or, } \frac{\partial W}{\partial h_o} = -\frac{3W}{h_o} \frac{B h_o^3}{B h_o^3 + k_c}$$

Lower value of k_c
increases stiffness



Orifice Compensation

$$Q_o = \frac{\pi d_o^2}{4} C_d \sqrt{2(P_s - P_r) / \rho} \Rightarrow Q_o = k_o \sqrt{(P_s - P_r)}$$

$$Q = \frac{\pi h_o^3 P_r}{6\eta \log(R_o / R_i)} \Rightarrow Q = B h_o^3 P_r$$

$$Q = Q_o$$

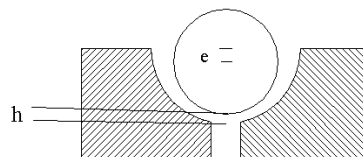
$$\Rightarrow \frac{P_r}{P_s} = \frac{k_o^2}{B^2 h_o^6 P_r + k_o^2}$$

$$W = P_r \left(\pi R_o^2 \left(\frac{1 - R_i^2 / R_o^2}{2 \log(R_o / R_i)} \right) \right) \Rightarrow A_{eff} P_r$$

$$\Rightarrow W = A_{eff} \left[\frac{-k_o^2 + k_o \sqrt{k_o^2 + 4B^2 h_o^6 P_s}}{2B^2 h_o^6} \right]$$

Hydrostatic Lift

- Useful to avoid metal to metal contact under heavy static load conditions. Ex. Synchronous condenser, rolling mills, etc.
- How to estimate load capacity ?



Elemental flow rate

$$\delta q = - \frac{h^3}{12\eta} \frac{dp}{r d\theta} \cdot b$$

$$h = C_r - e \cos \theta$$

- Trial and error method
 - Good for first of its kind.
- Numerical modeling and simulation
 - Assume a shaft of radius r being floated in a bearing of radius R by oil pumped through a slot at pressure P_s

Hydrostatic lift.....

$$h = C_r - e \cos \theta \rightarrow h = C_r (1 - \varepsilon \cos \theta)$$

Elemental flow rate $\varepsilon = e / C_r$

$$\delta q = -\frac{C_r^3 (1 - \varepsilon \cos \theta)^3}{12\eta} \frac{dp}{rd\theta} b$$

Elemental pressure rise

$$dp = -\frac{12r\eta q_1}{bC_r^3} \frac{d\theta}{(1 - \varepsilon \cos \theta)^3}$$

General solution

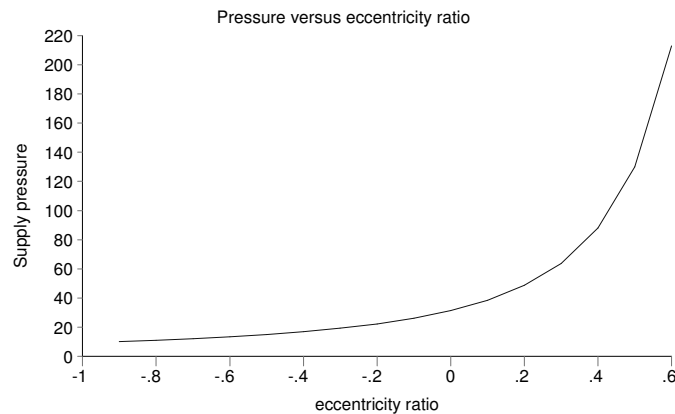
$$P = -\frac{12r\eta q_1}{bC_r^3} \left[\frac{\varepsilon \sin \theta (4 - \varepsilon^2 - 3\varepsilon \cos \theta)}{2(1 - \varepsilon^2)^2 (1 - \varepsilon \cos \theta)^2} + \frac{2 + \varepsilon^2}{2(1 - \varepsilon^2)^{2.5}} \cos^{-1} \left(\frac{\varepsilon - \cos \theta}{1 - \varepsilon \cos \theta} \right) + D \right]$$

constant of integration, D, can be evaluated using $P = 0$ at $\theta = 90^\circ$

$$D = -\left[\frac{\varepsilon(4 - \varepsilon^2)}{2(1 - \varepsilon^2)^2} + \frac{2 + \varepsilon^2}{2(1 - \varepsilon^2)^{2.5}} \cos^{-1}(\varepsilon) \right]$$

supply pressure P_s can be determined using $P = P_s$ at $\theta = 0^\circ$

$$P_s = \frac{12r\eta q_1}{bC_r^3} \left[\frac{\varepsilon(4 - \varepsilon^2)}{2(1 - \varepsilon^2)^2} + \frac{2 + \varepsilon^2}{2(1 - \varepsilon^2)^{2.5}} \cos^{-1}(\varepsilon) \right]$$



Negative value of eccentricity ratio, describe the journal position when it is above the bearing center.

Load Carrying Capacity

Pressure p acts on area $rd\theta.b$ and vertical component of force $prd\theta.b.\cos\theta$ will balance the applied load W

$$\therefore W = 2 \int_0^{\pi/2} br p \cos\theta . d\theta$$

$$W = -\frac{24r^2\eta q_1}{C_r^3} \int_0^{\pi/2} \left[\frac{\varepsilon \sin\theta (4 - \varepsilon^2 - 3\varepsilon \cos\theta)}{2(1 - \varepsilon^2)^2 (1 - \varepsilon \cos\theta)^2} + \frac{2 + \varepsilon^2}{2(1 - \varepsilon^2)^{2.5}} \cos^{-1} \left(\frac{\varepsilon - \cos\theta}{1 - \varepsilon \cos\theta} \right) \right] \cos\theta . d\theta$$

$$\rightarrow W = \frac{12\eta r^2 q_1}{C_r^3} \left[\frac{2 - \varepsilon}{(1 - \varepsilon)^2} \right]$$

